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COMPLETELY CONSISTENT 'NO-CHARGE' PHEMT MODEL INCLUDING DC/RF DISPERSION

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Abstract — A new large-signal PHEMT model based on independent fitting of DC currents, RF currents, and capacitances is developed. Unlike conventional models, it does not contain charge terms and therefore, avoids the problem of path-dependence in the charge-integration of capacitances. Similar consideration is given to the dispersion of conductances. Since each nonlinear element of the model corresponds to an element of the small-signal equivalent circuit, the model shows complete consistency over the bias range of the model's extraction. The model features accuracy and simplicity of extraction. It is especially useful for PHEMTs or FETs with dispersion.

I. INTRODUCTION

Large-signal FET/PHEMT modeling has advanced to a mature stage. Various empirical and table-based models have been developed [1-7] and are widely used. High accuracy has been achieved for those devices that satisfy charge conservation and show insignificant dispersion. Several papers [10-12] have dealt with dispersion with limited success.

The major difficulty is that conventional large-signal models that fit DC IV and QV characteristics are often inconsistent with small-signal models. Small-signal models derived from large-signal models have different values from those extracted from S-parameters. The currents and charges obtained from integration of measured small-signal element values are normally not unique because of the integration path-dependence due to dispersion.

The new model proposed here, has several features. (1) It does not contain charge terms and all the elements are nonlinear currents, including capacitive currents. (2) RF conductance and RF-trans-conductance values are different from those at DC. (3) The nonlinear functions can be independently extracted from a table of bias-dependent small-signal element values. (4) The functions have high-order continuous derivatives. The first two features ensure complete consistency with conventional small-signal models, since they have an exact correspondence between the model elements. A small-signal model derived from a conventional large-signal model contains as many as four trans-capacitance elements that makes the above consistency very difficult.

In the new model there is no ambiguity involved because there are no trans-capacitance terms, except for one that translates to a delay time in connection with G_m . The third feature simplifies the model extraction. Finally, the last feature ensures fast convergence and accurate two-tone simulations.

II. EQUIVALENT CIRCUIT MODEL

The charge terms in conventional models can be replaced with capacitive currents. Filicori, et. al. in their elegant paper [9], proved that any nonlinear circuit can be reduced to a network consisting of nonlinear resistances or current sources and linear capacitances.

For complete consistency, the current flowing into branch i , in addition to the DC terms, is divided into two classes of currents: conductive currents, such as drain currents I_{rf1} and I_{rf2} , and capacitive currents $\sum_j C_{ij} \cdot dv_j/dt$, where $i=j$ are local terms and $i \neq j$ are non-local terms, and v_j is the RF voltage across the j -th branch. To separate the DC V_{j0} from the instantaneous V_i and to create a voltage node dv_j/dt , the sub-circuits in Figure 1 are used. We denote V_g and V_d as instantaneous gate and drain voltages, and V_{g0} and V_{d0} as their DC components.

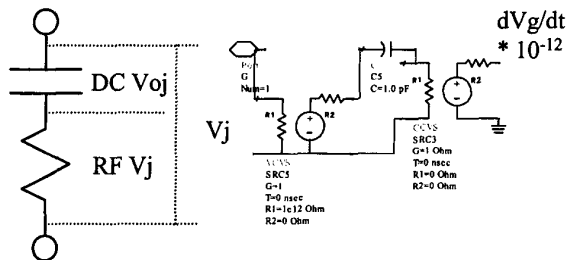
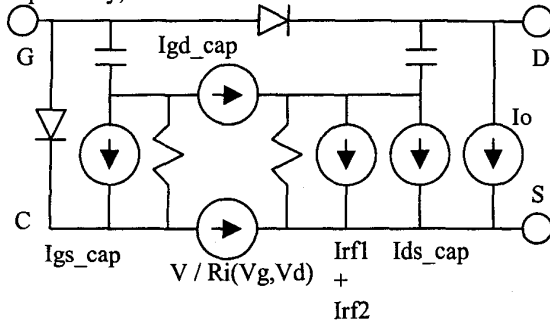


Figure 1. Sub-circuits to obtain DC V_{j0} , RF V_j and dV_j/dt .

Figure 1 shows how to obtain the respective voltage sources. The DC component of a branch voltage is taken from the capacitance of a series-RC shunted across the branch, assuming $RC \gg 1/f$ and $R \gg 1$ Mohm. The dV_j/dt is obtained in a slightly tricky manner. First apply the voltage V_j on a 1pF capacitance, and the current through the capacitance is exactly dV_j/dt times the factor of $1e-12$. Here, we use 1pF instead of a 1F to reduce the numerical

Moreover, the charge terms are eliminated altogether, making the model extraction much easier and faster.

where I_{ds_cap} , I_{gd_cap} and I_{gs_cap} are the capacitive currents flowing through branches D-S, D-G and G-S, respectively, and $C_m = G_m \cdot \tau_{eff}$.



III. MODEL EXTRACTION

$$I_{ds} = I_o \exp(-c P_{av}) (1 + \tanh((V_{gs} - V_{go}) / V_{det}))$$

$$I_o = \frac{I_{max}}{2} (1 + \tanh \phi) (1 + k V_{ds}) \tanh((a + \eta(0.95 - V_{gs})) V_{ds})$$

$$x = V_{ge} - V_{to} + V_{ds} \gamma$$

The functions for Cgs are expressed as

$$C_{\text{gsm}} = \frac{C_{\text{max}}}{2} (1 + \tanh \phi) (1 + kc(V_{\text{gs}} - V_k)),$$

$$x = V_{ds} - V_{cto}$$
$$C_{gd} = C_1 + \frac{(C_n - C_1)}{(1 + e^{((V_{gs} - V_o)/V_{gd}}))(1 + e^{((V_{ds} - V_{do})/V_{dd}})}$$

$$C_1 = C_{p1} + (C_{f1} - C_{p1}) / (1 + \exp(-(V_{gs} - V_{cl}) / V_{cd1}))$$

$$C_n = C_{pm} + (C_{fm} - C_{pm}) / (1 + \exp(-(V_{gs} - V_{c2}) / V_{cd2}))$$

$$V_{dd} = a_1 + a_2(1 - V_{gs})$$

Three current sources are combined to represent the DC and RF components. I_o , the DC current, and I_{rf1} and I_{rf2} , the RF conductive currents, are

$$\begin{aligned} I_{o1} &= -I_{dc}(V_g, V_d) + I_{dc}(V_{go}, V_d) + I_{dc}(V_g, V_{do}), \\ I_{rf1} &= I_{gm}(V_g, V_d) - I_{gm}(V_{go}, V_d), \text{ and} \\ I_{rf2} &= I_{gds}(V_g, V_d) - I_{gds}(V_g, V_{do}), \end{aligned}$$

where I_{gm} and I_{gds} are the D-S RF currents that fit the RF G_m and RF G_{ds} , respectively. They are obtained by integrating G_m and G_{ds} with respect to V_{gs} and V_{ds} along different integration paths [8]. The arguments of all the functions are the instantaneous port voltages and DC voltages. The current in the C-S branch is also used, where C denotes the internal node at the gate-end of the channel. The CR circuits are aimed at separating the DC and RF parts of the currents.

Assuming a small deviation of the port voltages and neglecting the higher-order term, one finds that the currents have the following correspondence to the elements of the small-signal model: $I_{gs_cap} \Rightarrow C_{gs}$, $I_{gd_cap} \Rightarrow C_{gd}$, $I_{ds_cap} \Rightarrow G_m \cdot \tau + C_{ds}$, $I_{rf1} \Rightarrow G_m$, and $I_{rf2} \Rightarrow G_{ds}$. The total current reduces to I_{dc} when $V_g = V_{go}$ and $V_d = V_{do}$. The derivatives of $I_{total} = I_{rf1} + I_{rf2} + I_o$ with respect to V_g and V_d reduce to the RF trans-conductance and drain-source conductance, respectively.

$$\begin{aligned} G_m &= \partial I_{\text{total}} / \partial V_g = \partial I_{gm} / \partial V_g \\ G_{ds} &= \partial I_{\text{total}} / \partial V_d = \partial I_{gds} / \partial V_d \end{aligned}$$

The model elegantly separates the DC components from RF-components, which gives consistency with small-signal models and accurate modeling of dispersion.

These equations are adequate to fit the table-data for the measured capacitances as functions of the port voltages.

As an example, 6x200um and 40x100um, 0.5um gate-length, Alpha D-PHEMTs are used. For such large devices, a complex topology of the equivalent circuit would be required to account for distributed effects. Nevertheless, a conventional model topology is used, and therefore, self-heating and other dispersion effects cannot be ignored because of the big differences between DC Gm/Gds and RF Gm/Gds and also because charge conservation does not apply. The S-parameters are measured over a bias range from below pinch-off to forward gate biases and with Vds from 0 to 5 V. The small-signal models are extracted using in-house program

ALPHAEXT which features fast direct extraction with no optimization involved.

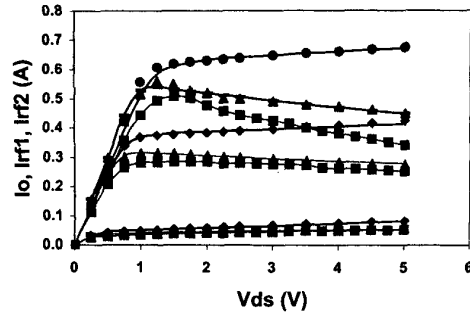


Figure 3. Measured (symbol) and fitted (line) dc IV, Igm and Igds. $V_g = -0.8, 0$ and 0.8 V. DC curves are squares, Igm curves are triangles, and Igds curves are diamonds.

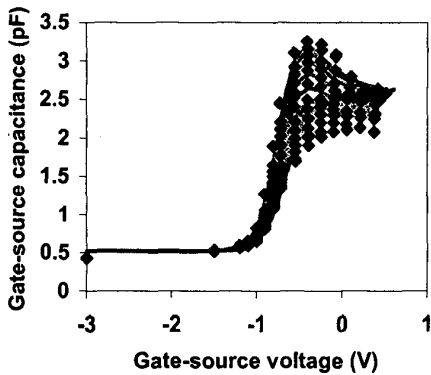


Figure 4. Fitted (line) and measured (symbol) C_{gs} as a function of V_g s and V_d s.

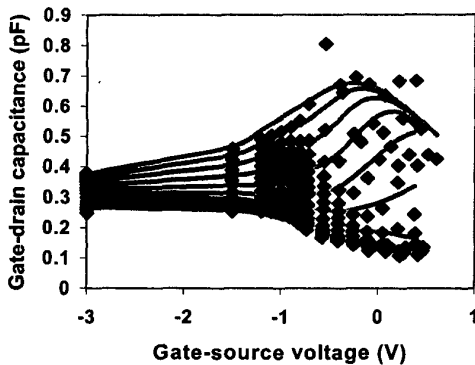


Figure 5. Fitted (line) and measured (symbol) C_{gd} as a function of V_g s and V_d s.

Figure 3 plots the measured and fitted DC IV curves as well as the Igm and Igds curves at three V_g values. It is shown that the Igm curves deviate from the DC IV curves

at higher gate voltages. The Igds curves are much different from both the Igm and the DC IV characteristics.

Figures 4 and 5 show very good fitting of C_{gs} and C_{gd} characteristics, respectively. Fitting of other parameter parameters is omitted here for the sake of brevity.

IV. MODELING RESULTS

To verify the consistency between the large-signal and small-signal models, S-parameter fitting is verified at various bias conditions. Figures 6 and 7 plot the modeled and measured S-parameters for the 6×200 μm device at several bias points: $V_g = 0.7$ V and -0.5 V and $V_d = 0.5$ V (linear region), $V_g = -1.5$ V and $V_d = 4$ V (below-pinch-off region), and $V_g = -0.8$ V and $V_d = 4$ V (saturation region).

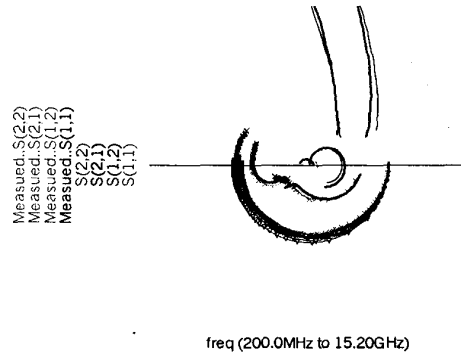


Figure 6. Model (line) versus measured (symbol) S_{11} , S_{22} , S_{12} , and S_{21} at four typical bias-points

Based on the model extracted from the 6×200 μm device, the model for a large 36×125 μm device was developed by linearly scaling the internal elements and nonlinearly scaling the extrinsic elements. Figure 8 shows the modeled and measured power performance at $f = 3.4$ GHz, source reflection = $0.5 \angle 179.2^\circ$, and load reflection = $0.57 \angle 152.4^\circ$ and $0.35 \angle 15.9^\circ$ at the fundamental and second harmonic, respectively. The device is biased at $V_g = -0.71$ V and $V_d = 5$ V. Very good agreement is achieved between the modeled and measured results.

It is noteworthy that the device is biased at $V_d = 5$ V, which is the upper end point of the bias range used for device characterization and model extraction. The voltage swing at high power drives can be as high as 11 V at the peak. Good agreement in the power performance prediction indicates that the equations used to fit the model parameters nicely extrapolate beyond the region of extraction.

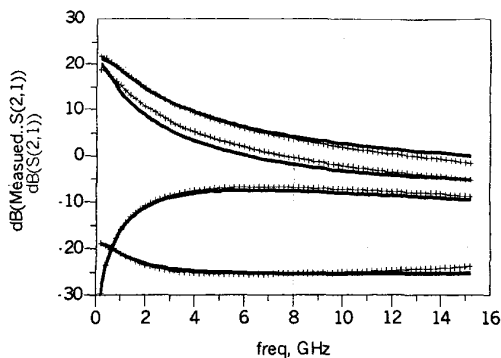


Figure 7. Model (line) vs measured (symbol) S21 in dB at four typical bias-points.

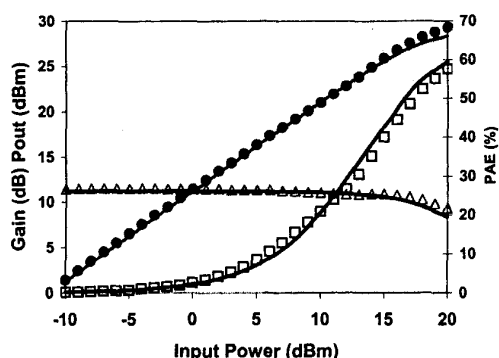


Figure 8. Simulated (line) vs measured (symbol) power performance of a 36x125 um PHEMT at $f = 3.4$ GHz, and $V_d = 5$ V, quiescent drain current is $I_{cq} = 0.1$ A.

V. CONCLUSION

A new MESFET/PHEMT model composed of only currents is developed. The new model is based on a one-to-one correspondence between the small-signal model elements and nonlinear functions of port voltages and therefore features consistency between the large-signal and small-signal models. Fitting of C_{gd} and C_{gs} is independent and does not require charge-conservation. Also, dispersion effects can be effectively handled since the RF G_{ds} and RF G_m can be different from the DC G_{ds} and DC G_m . The model is accurate, yet calculation-efficient. It is more complex and yet relatively simple to extract. At present, the model is empirical, but table-based models can be applied equally well. The model is especially useful for those devices, where dispersion and non-charge conservation are significant.

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